## Yi-Wei 'Daniel' Huang RESUME

updated December 31, 2017

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EDUCATION	
	Ph.D. (current) in Electrical and Control Engineering, National Chiao Tung University (NCTU),
	Taiwan.
	B.S. in Electrical Engineering and Computer Science Undergraduate Honors Program_National
	Chiao Tung University (NCTU), Taiwan.
PROJECTS	
	1) Outdoor Navigation for People Blind and Visually Impaired:
	Advisor: Prof. Hsueh-Cheng Nick Wang Summer, 2016
	The main notion of this project is to build a device that assist people who are blind and visually
	impaired while he/she is walking. A depth camera captures a disparity map as input, then follower
	by point cloud algorithms calculated in embedded systems and last, outputting vibration signals to
	the haptic belt. The system has several functionalities for instance, lane following, wall following,
	household object detection.
	2) Smart Coffee Cup (2015 ARM DESIGN CONTEST 1 <sup>st</sup> place): Fall, 2015
	This smart coffee cup is prototype for coffee perfectionists. It is capable to detect the flavor of the
	coffee including sweetness, how much cream, etc. Unlike common methods, it only grabs data
	from the tiny electrodes in the cup. It heavily uses signal processing, and SVM and other ML
	algorithms to analyze every factor in the coffee. A math model is built to simulate the cup of
	coffee.
	3) Vision-based multi-scooter velocity-measuring system: Spring, 2014
	The purpose of this project is to build a mobile system that is capable of simultaneously measuring
	the velocity of multiple scooters. It is based on computer vision and is invulnerable to various
	lighting conditions. And since it is mobile, I can mount it everywhere I want to. Test results held in
	the scooter-path of the campus were great.
<b>ACTIVITIES</b>	
	Founder and president of Maker club (Makereal Labs) at NCTU
	Cofounder of a Startup called flipMED in Taiwan. Won several competitions and prizes summing
	up to 70000USD. Our product is a hardware and service for Mobile Health.
<u>SKILLS</u>	
	Programming Language: C/C++, Python, Matlab, Java
	Middleware for Robotics: Robot Operation System (ROS), LCM
	Libraries and Toolbox: OpenCV, Point Cloud Library (PCL), CUDA
	Other Skills: 3DsMAX, 3D Printing and modeling
<b>RELEVANT</b>	
<u>COURSEWORK</u>	
	Digital Image Processing, Machine Learning and Pattern Recognition, Embedded Systems.
	Operating Systems Design and Implementation, Parallel Programming, Robotic Vision.